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LEVELLING TEST RESULTS

AND

THE SPACE FOR LEVELLING COMPROMISE

Prepared by Poland

LOAD - LEVELLING TEST

Performed on 13 September 2022 in LTIK Karlsruhe by IWG-SLR

Purpose of the test was to check what is precision of automatic levelling system of real cars as the base to verify aiming diagram ("box") horizontal size It was measured the relative change of cut-off inclination with respect to the initial setting (set as 0.00%)

Testing conditions

- 5 cars with automatic levelling system manufactured according existing Regulation No 48
- No special preparation of car (as they were)
- 4 different loading conditions from driver only up to maximum back load
- Measurements of reaction of automatic levelling to load change
- At the end of each test measurements were repeated for the first condition as the check of repeatability

TEST SUMMARY

Relative change of cut-off inclination (in %) in relations to initial value (0.00%)

+ up - down

Vehicle No	1L(eft)	1R(ight)	2L	2R	3L	3R	4L	4R	5L	5R
	neadlamp	neadlamp								
Load condition										
1	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%
Back to 1	-0,03%	-0,11%	-0,08%	-0,09%	-0,19%	0,02%	-0,07%	-0,12%	0,01%	0,00%
2	-0,31%	-0,31%	-0,40%	-0,32%	-1,07%	-0,99%	0,29%	0,20%	-0,04%	-0,06%
3	-0,32%	-0,32%	-0,45%	-0,24%	-1,19%	-1,08%	0,41%	0,29%	0,01%	0,11%
4	-0,31%	-0,34%	0,48%	0,81%	-0,40%	-0,14%	0,36%	0,31%	0,05%	0,18%

Vehicle	1L	. 1R	2L	2R	3L	3R	4L	4R	5L	5R
Load condition										
1	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%
Back to 1	-0,03%	-0,11%	-0,08%	-0,09%	-0,19%	0,02%	-0,07%	-0,12%	0,01%	0,00%
2	-0,31%	-0,31%	-0,40%	-0,32%	-1,07%	-0,99%	0,29%	0,20%	-0,04%	-0,06%
3	-0,32%	-0,32%	-0,45%	-0,24%	-1,19%	-1,08%	0,41%	0,29%	0,01%	0,11%
4	-0,31%	-0,34%	0,48%	0,81%	-0,40%	-0,14%	0,36%	0,31%	0,05%	0,18%

- It was checked the returning back to reference value behaviour of the vehicle and measuring setup repeatability.
- Value depend on precision of vehicle, its positioning on the stand, cut-off shape and sharpness
- Repeatability within 0.1% was obtained except one headlamp
- For the car No 5 the repeatability was 0.01% (perfect !).

Precision of automatic levelling

For vehicle 1, 4 and 5 system reaction is up to 0,4% in regard to initial value and nearly the same for left and right headlamp.

Vehicle	1L	1R	2L	2R	3L	3R	4L	4R	5L	5R
Load condition										
1	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%
Back to 1	-0,03%	-0,11%	-0,08%	-0,09%	-0,19%	0,02%	-0,07%	-0,12%	0,01%	0,00%
2	-0,31%	-0,31%	-0,40%	-0,32%	-1,07%	-0,99%	0,29%	0,20%	-0,04%	-0,06%
3	-0,32%	-0,32%	-0,45%	-0,24%	-1,19%	-1,08%	0,41%	0,29%	0,01%	0,11%
4	-0,31%	-0,34%	0,48%	0,81%	-0,40%	-0,14%	0,36%	0,31%	0,05%	0,18%

System of car No 2 and No 3 are excluded from further analysis:

- Meet existing requirements
- Do not react with expected precision
- Should also meet proposed requirements (<1.2%)
- Unknown technical details of system no possibility to check if it is feasible to narrow the range of reaction (after proper calibration ?)

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Vehicle	1L	1R	2L	2R	3L	3R	4L	4R	5L	5R
Load condition										
1	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%
Back to 1	-0,03%	-0,11%	-0,08%	-0,09%	-0,19%	0,02%	-0,07%	-0,12%	0,01%	0,00%
2	-0,31%	-0,31%	-0,40%	0,32%	-1,07%	-0,99%	0,29%	0,20%	-0,04%	-0,06%
3	-0,32%	-0,32%	-0,45%	-0,24%	-1,19%	-1,08%	0,41%	0,29%	0,01%	0,11%
4	-0,31%	-0,34%	0,48%	0,81%	-9,40%	-014%	0,36%	0,31%	0,05%	0,18%

Control of levelling by different load:

- Vehicle No 1 the same value (within 0.1%) for different load and slightly down (-0.3%), slightly overcompensated, very close values left and right headlamps
- Vehicle No 4 the value within 0.2%, slightly overcompensated
- Vehicle No 5 left within 0.1%, right within 0.2%

System can potentially control aim better than 0.05% (vehicle No 5 L)

For vehicle 1, 4 and 5 total system reaction (as it was) is up to 0,4% in regard to initial value and nearly the same for left and right headlamp.

After proper calibration total results should narrow to 0.1%... 0.2%

Vehicle	1L	1R	2L	2R	3L	3R	4L	4R	5L	5R
Load condition										
1	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%	0,00%
Back to 1	-0,03%	-0,11%	-0,08%	-0,09%	-0,19%	0,02%	-0,07%	-0,12%	0,01%	0,00%
2	-0,31%	-0,31%	-0,40%	-0,32%	-1,07%	-0,99%	0,29%	0,20%	-0,04%	-0,06%
3	-0,32%	-0,32%	-0,45%	-0,24%	-1,19%	-1,08%	0,41%	0,29%	0,01%	0,11%
4	-0,31%	-0,34%	0,48%	0,81%	-0,40%	-0,14%	0,36%	0,31%	0,05%	0,18%

CONCLUSIONS

- EXISTING AUTOMATIC LEVELLING SYSTEMS CAN CONTROL LEVELLING BETTER THAN POSSIBLE TO MEASURE (0.1 %)
- EXISTING AUTOMATIC LEVELLING SYSTEMS WITHOUT SPECIAL PREPARATION CAN CONTROL LEVELLING IN RANGE 0.4% WITH POTENTIAL POSSIBILITY TO NARROW DOWN TO 0.1 ... 0.2 % AFTER CALIBRATION
- THERE IS MUCH BETTER THAN NEEDED FOR PROPOSAL BELOW (0.5%...1.3%) AND THE WORST TESTED CAR CAN FIT THE PROPOSED RANGE

HOW TO OBTAIN "BOX" CONSENSUS IN GRE

What are the expectations and what can be accepted by Contracting Parties?

- Automatic levelling remove most "box" problems resulting from manual levelling design restriction
- By proper initial aim and narrow the levelling tolerances the glare will be significantly reduced and the road illumination distance will be increased
- Is it possible to find consensus on the base of laws of physics and real technical feasibility?
- Are there any particular (or hidden) expectations ? What kind of ?

HOW TO OBTAIN BOX COMPROMISE

Issues raised in IWG SLR:

- 1. Concerns about increase of glare / expectations to reduce glare
- 2. Increase the real minimum road illumination distance
- 3. Freedom to choice the initial aim anywhere inside the box
- 4. The same initial aim for different vehicle models (if obligatory)
- 5. Keep the previously proposed box, whether it's good or bad
- 6. Manufacturers can make good lights so they don't want restrictions
- 7. Any other?
- 8.

RATIONALES FOR "BOX" BOUNDARIES AND SPACE FOR A COMPROMISE

First:

The need to obtain valuable results for long time

There is no need to compare optimised box with "old box" or "last proposed box" (GRE/2020/8/rev.2) because they use partially artificial lines adapted to presently existing <u>manual levelling</u> idea





Second:

Try to understand what really mean each "box" line in regard to traffic safety and start to think in safety determinants

Third:

Take into account that the <u>automatic levelling</u> is "different animal" than the <u>manual levelling</u> and allow to control the aim with precision even to 0.1% when 0.4% is not a particular challenge. Better then 1.0 % is effortlessly achievable

SPACE FOR A COMPROMISE – right "box" boundary ROAD ILLUMINATION DISTANCE LINE



Aiming (%)

SPACE FOR A COMPROMISE – ROAD ILLUMINATION DISTANCE



Aiming (%)

Headlamp mounting height (m)



Headlamp mounting height (m)



GLARE SIDE

for low mounted headlamps cut-off under horizon

Added safety margin -0.5%

Aiming (%)

High mounted headlamps



Glare cannot be completely avoided with higher-mounted headlamps

Decision should be make what distance of unavoided glare could be accepted - space for the compromise





FORMULA: $I = \Delta h / L_{min}$

I - cut-off inclination

 Δh - headlamp optical axis height over minimum eye-height

L_{min} - maximum distance beyond the vehicle where glare is accepted (25 m)



Aiming (%)





OPTIMAL BOX FOR SAFETY



Headlamp mounting height (m)

Aiming (%)

OPTIMAL BOX up to 1.2m MOUNTING HEIGHT – READY TO USE

Headlamp mounting height (m)

CHECK IF THE "BOX":

- GUARANTEE THE SAFETY
 AND
- IS TECHNICALLY FEASIBLE



SPACE FOR A COMPROMISE - IF REALLY NEEDED?

Headlamp mounting height (m)

THE COMPROMISE SHOULD BE EXPRESSED IN METERS ON THE ROAD



Aiming (%)

HIGHER MOUNTED HEADLAMPS (OFF-ROAD VEHICLES)

Headlamp mounting height (m)



For higher mounted headlamps (off-road) is higher glare risk but because of usual lower speed the road illumination distance can be reduced to [35]m giving more space for manual leveling up to 2.0%

INITIAL AIM – fixed or free?

- FIXED IN RELATION TO THE HEIGHT is needed when "box" is defined arbitrary in separation from the laws of physics
 ADVANTAGE: No need to require initial aim for vehicle type (no label)
- CAN BE FREE INSIDE THE BOX when box truly control road illumination and glare but require do be assigned to the vehicle model

Headlamp mounting height (m)

INITIAL AIM FIXED IN RELATION TO THE HEIGHT - NO INITIAL AIM VALUE ON THE VEHICLLE

WITHOUT CALIBRATION (AS IT IS)

Vehicle	1L	1R
Load		
condition		
1	0,00%	0,00%
2	-0,31%	-0,31%
3	-0,32%	-0,32%
4	-0,31%	-0,34%



INITIAL AIM FIXED IN RELATION TO THE HEIGHT - NO INITIAL AIM VALUE ON THE VEHICLLE

WITH PROPER CALIBRATION

Vehicle	1L	1R
Load		
condition		
1	0,00%	0,00%
2	0,00%	0,00%
3	0,00%	0,00%
4	0,00%	0,00%



INITIAL AIM FIXED IN RELATION TO THE HEIGHT - NO INITIAL AIM VALUE ON THE VEHICLLE

WITH CALIBRATION MEASUREMENTS UNCERTAINTY ADDED

Vehicle	1L	1R
Load		
condition		
1	0,00%	0,00%
2	±0,10%	±0,10%
3	±0,10%	±0,10%
4	±0,10%	±0,10%





FREE INITIAL AIM - INITIAL AIM VALUE ON THE VEHICLLE

Headlamp mounting height (m)

WITHOUT CALIBRATION (AS IT IS)

Vehicle	1L	1R
Load		
condition		
1	0,00%	0,00%
	0.2404	0.040/
2	-0,31%	-0,31%
3	-0,32%	-0,32%
	,	,
4	-0,31%	-0,34%



FR- INITIAL AIM VALUE ON THE VEHICLLE EE INITIAL AIM

Headlamp mounting height (m)

WITH CALIBRATION MEASUREMENTS UNCERTAINTY ADDED

Vehicle	1L	1R
Load		
condition		
1	0,00%	0,00%
2	-0,31%	-0,31%
3	-0,32%	-0,32%
4	-0,31%	-0,34%



Headlamp mounting height (m)

INITIAL AIM FIXED IN RELATION TO THE HEIGHT - NO INITIAL AIM VALUE ON THE VEHICLLE

WITHOUT CALIBRATION (AS IT IS)

Vehicle	4L	4R
Load		
condition		
1	0,00%	0,00%
2	0,29%	0,20%
3	0,41%	0,29%
4	0,36%	0,31%



Headlamp mounting height (m)

INITIAL AIM FIXED IN RELATION TO THE HEIGHT - NO INITIAL AIM VALUE ON THE VEHICLLE

WITH PROPER CALIBRATION

		40
venicie	4L	48
Load		
condition		
1	0,00%	0,00%
2	0,00%	0,00%
3	0,00%	0,00%
4	0,00%	0,00%



INITIAL AIM FIXED IN RELATION TO THE HEIGHT - NO INITIAL AIM VALUE ON THE VEHICLLE

WITH CALIBRATION MEASUREMENTS UNCERTAINTY ADDED

Vehicle	4L	4R
Load		
condition		
1	0,00%	0,00%
2	±0,10%	±0,10%
3	±0,10%	±0,10%
4	±0,10%	±0,10%



FREE INITIAL AIM - INITIAL AIM VALUE ON THE VEHICLLE

Headlamp mounting height (m)

WITHOUT CALIBRATION (AS IT IS)

Vehicle	4L	4R
Load		
condition		
1	0,00%	0,00%
2	0,29%	0,20%
3	0,41%	0,29%
4	0,36%	0,31%



FREE INITIAL AIM - INITIAL AIM VALUE ON THE VEHICLLE

Headlamp mounting height (m)

WITH CALIBRATION MEASUREMENTS UNCERTAINTY ADDED

Vehicle	4L	4R
Load		
condition		
1	0,00%	0,00%
2	±0,10%	±0,10%
3	±0,10%	±0,10%
4	±0,10%	±0,10%

