Presentation 1
1st GoE on LIAV, 1 September 2021
Provisional agenda item 4

The need of a GE.3-model of a safe use of automated vehicles in traffic to support drafting a new legal instrument

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"...safety focuses on the proper functioning of a system.."

In "Safety first for automated driving (2019)" p.21

SAFETY FIRST FOR AUTOMATED DRIVING

https://www.daimler.com/documents/innovation/other/safety-first-for-automated-driving.pdf

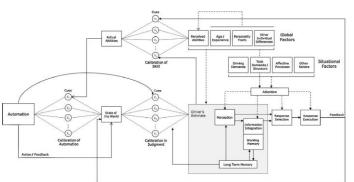


Examples among many others....

GDE-model (Goals for Driver Education)

| | Knowledge and skills | Risk-increasing factors | Selfevaluation |
|--|--|---|---|
| Goals for life, skills for living (general) | Lifestyle, age, group norms, motives, self- control, personal values | Sensation seeking Group norms Complying to social pressure Use of alcohol | Risky tendencies Personal skills for impulse control Safety negative motives |
| Goals and context of driving (trip related) | Modal choice Choice of time Trip goals Social pressure | Alcohol, fatigue Purpose of driving Rush hours Extra motives: competing | Planning skills Typical goals Typical risky motives |
| Mastery of traffic situations | Traffic rules Observation Driving path Communication | Disobeying rules Information overload Unsuitable speed. | Awareness of personal strengths and weaknesses |
| Vehicle manoeuvring | Control of direction, position Tyre grip Physical laws | Unsuitable speed Insufficient automatism Difficult conditions | Strong and weak points of basic manoeuvring |

4) Hatakka, M., Keskinen, E., Gregersen, N. P., & Glad, A. (1999). Theories and aims of educational and training measures. (Bfu Report No. 40). In S. Siegrist (Ed.), Driver training, testing and Licensing - Towards theory-based management of young drivers' injury risk in road traffic. Results of EU-Project GADGET, Work Package 3.



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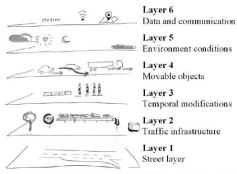
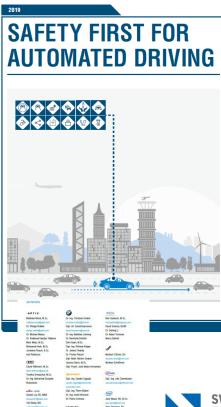


Figure 1. Six-layer model for scenarios (Bock et al. 2018) (reprinted with permission).



conceptual framework and the implications for road safety William J. Horrey a. Mary F. Lesch b, Eve Mitsopoulos-Rubens c, John D. Lee d





Dr. Thomas Milachia

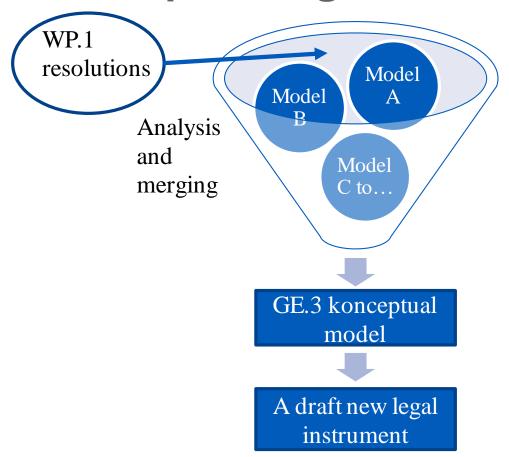
Dipli-Int. States Publisher Dr. Ing. Kol Sedaczek

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Fig. 3. Framework for examining calibration in driving, expanded to show the role and influence of automation (on the left hand side of the figure).

Expressing a konceptual GE.3-model



- Quality assurance
- Effectiveness
- Efficiency
- Transparancy
- Support changes over time
- Etc.

