**Allocation of the priorities (ECE/TRANS/WP.29/2019/2) to IWGs of GRVA**

The table below was drafted and agreed by GRVA at the end of its 2nd session as a consolidation of inputs made by the Contracting Parties during the discussions at this GRVA session, with the expectation that this provide a base for continued discussions at the March 2019 session of WP29. It allocates the priorities (ECE/TRANS/WP.29/2019/2) to IWGs of GRVA and defines indicative deadlines for these priorities in order to guide the Chairs of IWGs. It recalls that GRVA authorizes the IWGs to work while the final Terms of References will be further developed to reflect the decisions taken by GRVA after endorsement of WP.29.

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| *Task* | *Allocation to* | *FRVA* | *VMAD* | *CS/OTA* | *New IWG* | *Deadline* |
| **Framework document on automated/autonomous vehicles** | GRVA (supported by webex meetings) |  |  |  |  | 2 months |
| **Functional****Requirements for****automated /****autonomous vehicles** | FRVA \*(\* working under the former mandate of the IWG on ACSF) | X |  |  |  | 36 months  |
| ALKS | FRVA | X |  |  |  | 12 months |
| **New Assessment / Test Methods** | VMAD\*\*(\*\* working under the temporary general mandate proposed in informal doc GRVA-02-14) |  | X |  |  | [December 2020] |
| Requirements for functional safety“CEL” | VMAD |  | X |  |  | ALKS: 12 months |
| **Cyber security and (OTA) software updates** | CS/OTA\*\*\*(\*\*\* working under the current mandate, extended to perform the test phase) |  |  |  |  | 12 months |
| **DSSAD**Specific for ALKS | FRVA (or subgroup) | X |  |  |  | DSSAD for ALKS: 12 months |
| General | New group |  |  |  | X | Review in September 2019(incl. Clear objectives, deadline and the identification of differences with EDR to be determined first before discussion on detailed data information) |

Note:

* FRVA is the new Informal Working Group on Functional Requirements for Automated/Autonomous Vehicles
* VMAD is the new Informal Working Group on the Validation Method for Automated Driving