## Proposal for amendments to UN Regulation No. 13

# Submitted by the experts from the International Organization of Motor Vehicle Manufacturers

# I. Proposal

Annex 6, Appendix, paragraph 3., amend to read:

"3. Example of a simulator for electric control lines

(Figure unchanged)

ECL = Electric Control Line corresponding to ISO 7638

SIMU = Simulator of Byte 3,4 of EBS 11 according to ISO 11992**-2:2003 including its** 

amendment 1-2007 with output signals at start, 65 kPa and 650 kPa

A = Supply connection with shut-off valve

C2 = Pressure switch to be connected to the brake actuator of the trailer, to

operate at 75 per cent of the asymptotic pressure in the brake actuator CF

CF = Brake cylinder M = Pressure gauge

PP = Pressure test connection
TA = Coupling head, supply line
VRU = Emergency relay valve"

Annex 13, footnote 11, amend to read:

"11  $k_{\text{H}}$  is the high adhesion surface coefficient.

k<sub>L</sub> is the low adhesion surface coefficient.

k<sub>H</sub> and k<sub>L</sub> are measured as laid down defined in Appendix 2 to this annex."

Annex 16, paragraph 2.4.1., delete footnote 2 and renumber footnotes 3 and 4 as footnotes 2 and 3.

Annex 16, paragraph 2.4.2., delete footnotes 5 and 6.

Annex 19, paragraph 4.4.2.9., amend to read:

"4.4.2.9. If the manufacturer ...

The details of any additional conditioning shall be recorded and appended to the brake factor  $B_F$  in paragraph 2.3.1. of Annex 11, Appendix 3, by specifying for instance the following test parameters:

- (a) Brake actuator pressure, the brake input torque or the brake **output** torque of the brake application;
- (b) Speed at the beginning and the end of the brake application;
- (c) Time in the case of a constant speed;
- (d) Temperature at the beginning and the end of the brake application or the duration of the brake cycle."

## II. Justification

## Annex 6, Appendix, paragraph 3

Byte 3-4 of EBS 11 is only referenced in Part 2 of ISO 11992, therefore the text should make that reference along with amendment 1:2007.

#### Annex 13, footnote 11

 $k_{\text{H}}$  and  $k_{\text{L}}$  are already defined in Appendix 1 "Symbols and Definitions" and are therefore unnecessary.

#### Annex 16, paragraph 2.4.1.

Existing footnote 2 is identical to footnote 1.

## Annex 16, paragraph 2.4.2.

Footnote 5 is identical to footnote 2 and footnote 6 is identical to footnote 3.

## Annex 19, paragraph 4.4.2.9.

Adding "output" clarifies what is intended.